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INTRODUCTION

This document presents relevant data sheets and technical specifications for all tracked plant currently operated by Sheet Piling (UK) Ltd.

This includes Telescopic Leader Rigs, Excavator Piling Rigs and Crawler Cranes.

The purpose of the document is to assist Contractors, Developers, Clients and Engineers in various Health & Safety technical submissions and Temporary Works designs required for contractual and third party approvals to carry out sheet piling works on any particular project.

Plant loading information is presented for all tracked plant in the format required for Working Platform Designs to the BRE Digest 470 'Working Platforms for Tracked Plant'.

Also included is technical information on Noise and Vibration Assessments for vibratory installation.

"As one of the UK's leading driven steel piling contractors, Sheet Piling (UK) Ltd has built its reputation on solid foundations."



Version 6: Updated June 2022



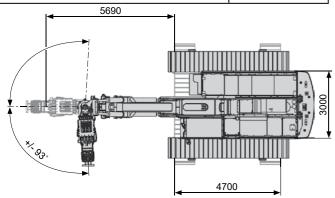
ABI TM 20 LONG REACH RIG

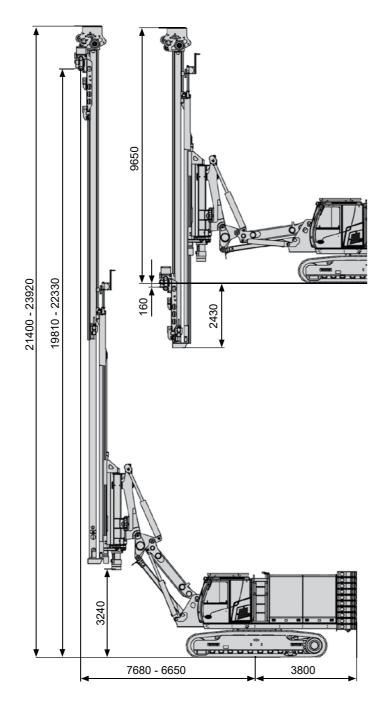
Base Carrier	SR35 F (HD)
Engine Type	CAT C18
Engine Power	470 kW
Operating Weight	84.5 tonnes
Transport Weight	79.1 tonnes

Telescopic Leader Mast	TM 20
Total Height	23.92 m
Maximum Pile Length	20.0 m
Crowd Force	180 kN
Extraction Force	180 kN

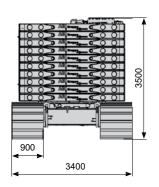
Vibro Hammer	MRZV 30VV
Static Moment	0-30 kgm
Docking System	D6
Frequency	2140/minute
Centrifugal Force	1500 kN
Weight	5390 kg

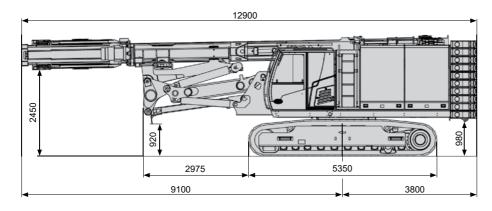
Augering	
Auger Model	MDBA 7000
Torque	7.0 tonnes





DIMENSIONS: TRANSPORTATION



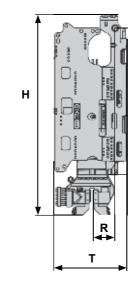


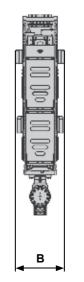






VIBROHAMMER: MRZV 30VV with D6 Docking Station





Vibro Hammer	MRZV 30VV
(H) Length	3405 mm
(B) Width	790 mm
(T) Depth	1465 mm
(R) Guide to Driving Axle	360 mm



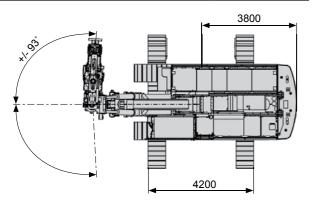
ABI TM 20 LEADER RIG

Base Carrier	SR35 F
Engine Type	CAT C18
Engine Power	470 kW
Operating Weight	69.6 tonnes
Transport Weight	64.8 tonnes

Telescopic Leader Mast	TM 20
Total Height	24.65 m
Maximum Pile Length	20.0 m
Crowd Force	200 kN
Extraction Force	235 kN

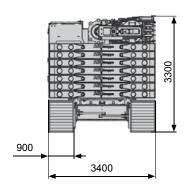
Vibro Hammer	MRZV 30VV
Static Moment	0-30 kgm
Docking System	D6
Frequency	2140/minute
Centrifugal Force	1500 kN
Weight	5390 kg

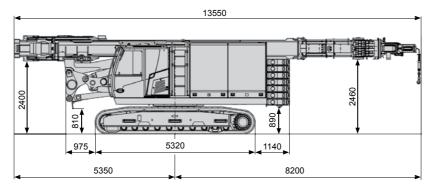
Augering	
Auger Model	MDBA 7000
Torque	7.0 tonnes

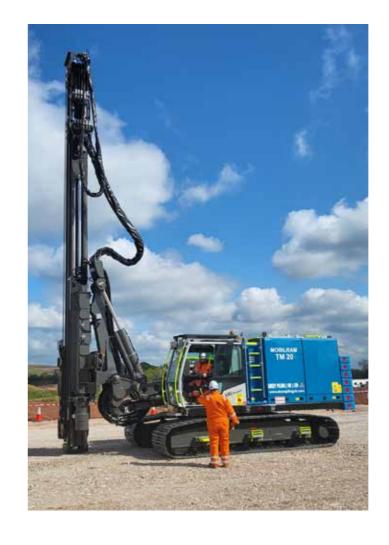


22125 - 24650 19710 - 22230 19710 - 22230 2560

DIMENSIONS: TRANSPORTATION



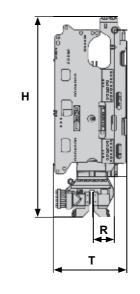








VIBROHAMMER: MRZV 30VV with D6 Docking Station





Vibro Hammer	MRZV 30VV
(H) Length	3405 mm
(B) Width	790 mm
T) Depth	1465 mm
(R) Guide to Driving Axle	360 mm

 6



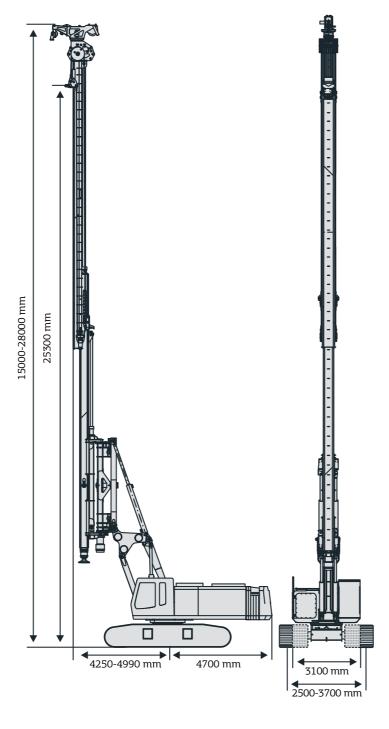
ABI TM 18/22 HD LEADER RIG

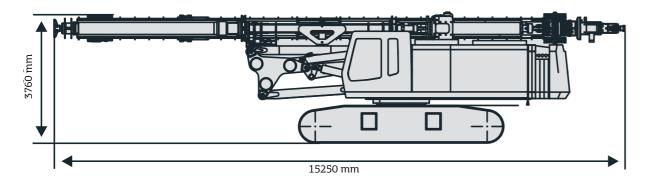
Base Carrier	SR 50 T
Engine Type	CAT C18
Engine Power	570 kW
Operating Weight	75 tonnes
Transport Weight	70 tonnes

Telescopic Leader Mast	TM 18/22 HD
Total Height	28.00 m
Maximum Pile Length	22.0 m
Crowd Force	120 kN
Extraction Force	200 kN

Vibro Hammer	MRZV 30V
Static Moment	0-30 kgm
Amplitude	15.5 mm
Frequency	2135/minute
Centrifugal Force	1500 kN
Weight	5350 kg

Augering	
Auger Model	MDBA 7000
Torque	7 tonnes



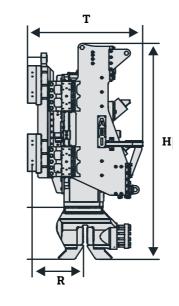


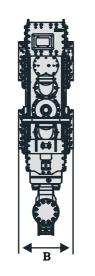






VIBROHAMMER: MRZV 30V





/ibro Hammer	MRZV 30V
H) Length	3220 mm
B) Width	690 mm
T) Depth	1525 mm
R) Guide to Driving Axle	650 mm



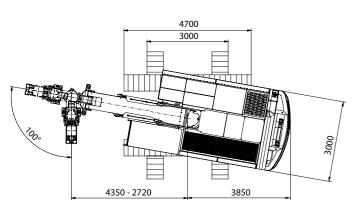
ABI TM 13/16 SL LEADER RIG

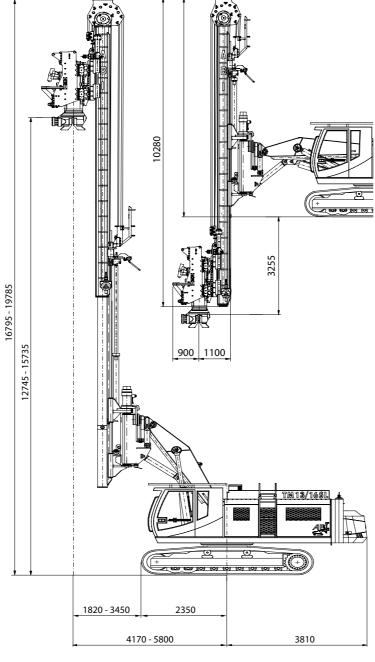
Base Carrier	SR35 T-E
Engine Type	CAT C15
Engine Power	433 kW
Operating Weight	50 tonnes
Transport Weight	45 tonnes

Telescopic Leader Mast	TM 13/16 SL
Total Height	19.8 m
Maximum Pile Length	16 m
Crowd Force	90 kN
Extraction Force	175 kN

Vibro Hammer	MRZV 25VV
Static Moment	0-25 kgm
Amplitude	18.0 mm
Frequency	1910/minute
Centrifugal Force	1350 kN
Weight with Clamp	4170 kg

Augering	
Auger Model	MBDA 4000
Torque	4 tonnes



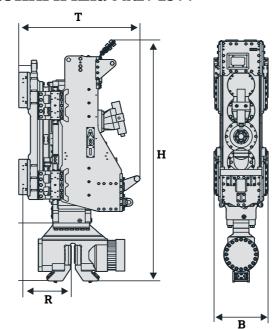






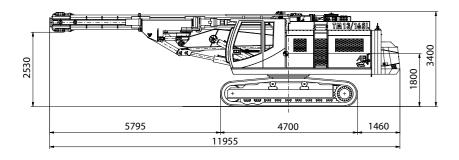


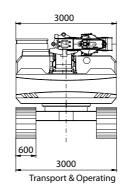
VIBROHAMMER: MRZV 25VV



Vibro Hammer	MRZV 25VV
(H) Length	3085 mm
(B) Width	690 mm
(T) Depth	1345 mm
(R) Guide to Driving Axle	650 mm

DIMENSIONS: TRANSPORTATION







ABI TM 12/15 LONG REACH

ABI TM 12/15 - **STANDARD REACH** CONFIGURATION

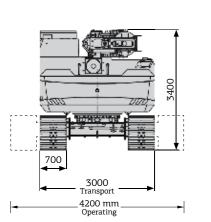
Base Carrier	SR 30 T-E
Engine Type	Scania DC9
Engine Power	294 kW
Operating Weight	59 tonnes
Transport Weight	55 tonnes

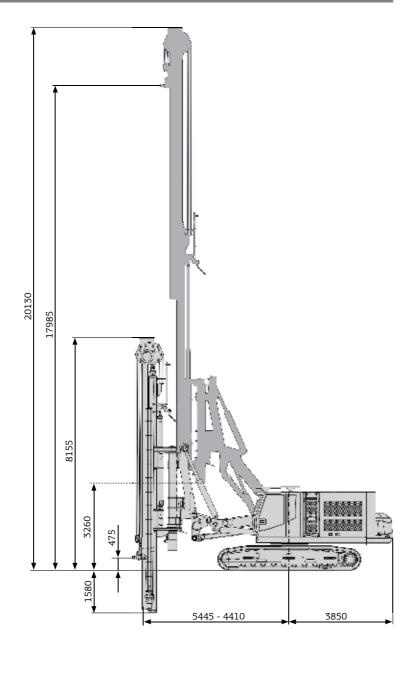
Telescopic Leader Mast	TM 12/15
Total Height	20.1 m
Maximum Pile Length	15 m
Crowd Force	90 kN
Extraction Force	175 kN

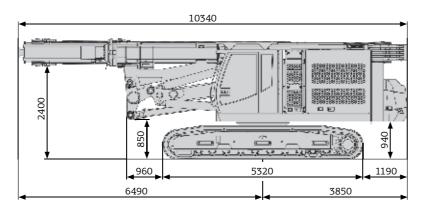
Vibro Hammer	MRZV 20VV
Static Moment	0-20 kgm
Amplitude	16.0 mm
Frequency	2135/minute
Centrifugal Force	1200 kN
Weight with Clamp	4220 kg

Augering	
Auger Model	MBDA 4000
Torque	4 tonnes









LEADER RIG

ABI TM 12/15 - LONG REACH CONFIGURATION

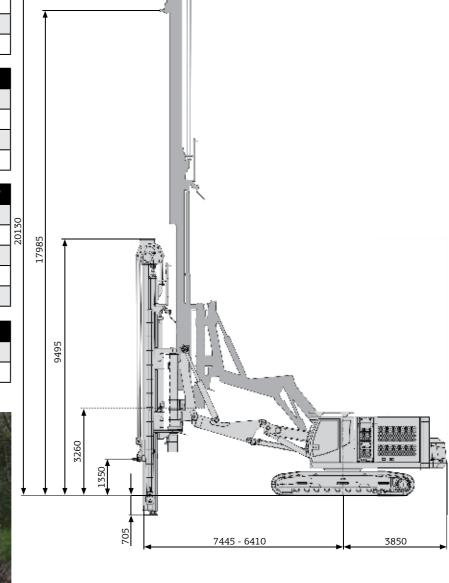
Base Carrier SR 30 T-E	
Engine Type	Scania DC9
Engine Power	294 kW
Operating Weight	61 tonnes
Transport Weight	57 tonnes

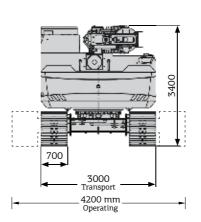
Telescopic Leader Mast	TM 12/15
Total Height	20.1 m
Maximum Pile Length	15 m
Crowd Force	90 kN
Extraction Force	100 kN

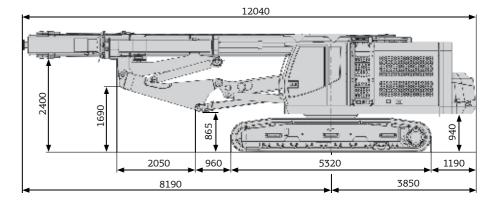
Vibro Hammer	MRZV 20VV
Static Moment	0-20 kgm
Amplitude	16.0 mm
Frequency	2135/minute
Centrifugal Force	1200 kN
Weight with Clamp	4220 kg

Augering	
Auger Model	MBDA 4000
Torque	4 tonnes











BAUER RTG 21 LEADER RIG

Base Carrier	BS 60-RS
Engine Type	CAT C18
Engine Power	570 kW
Operating Weight	78 tonnes
Transport Weight	73 tonnes

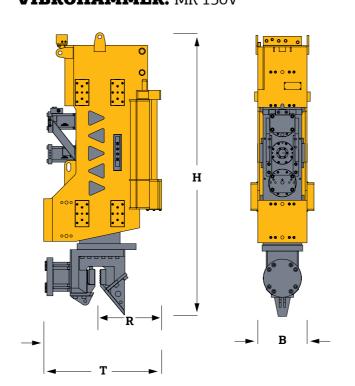
Telescopic Leader Mast	RTG 21
Total Height	26.8 m
Maximum Pile Length	21 m
Crowd Force	140 kN
Extraction Force	260 kN

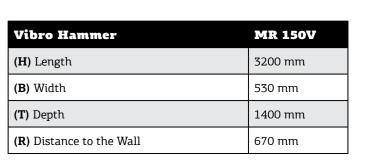
Vibro Hammer	MR 150V
Static Moment	0-28.4 kgm
Amplitude	18.0 mm
Frequency	2200/minute
Centrifugal Force	1500 kN
Weight	6000 kg

Augering	
Auger Model	BK60
Torque	6 tonnes







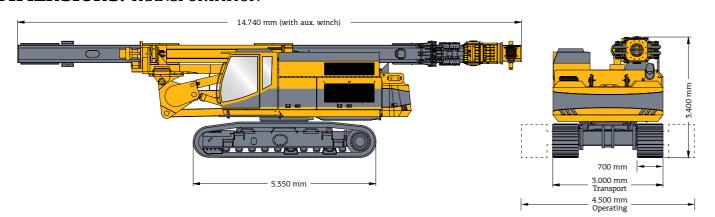








DIMENSIONS: TRANSPORTATION



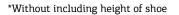


KOBELCO SK350 LC EXCAVATOR RIG

Base Machine	chine SK350 LC		
Engine Type	HINO JO8EYD-KSSA		
Engine Power	213 kW		
Fuel Tank	503 litres		
Hydraulic Tank	410 litres		
Undercarriage	Fixed		
Operating Weight	36.6 tonnes		

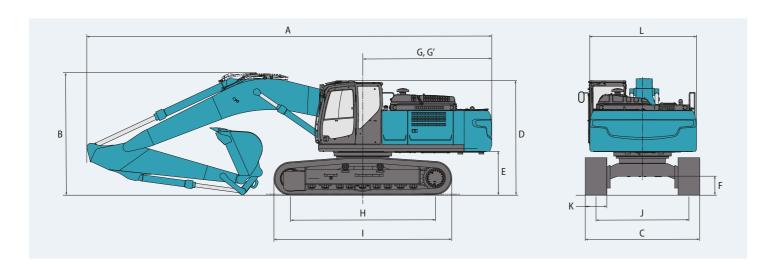
Vibro Hammer	Movax SG75
Static Moment	7.6 kgm
Frequency	2300-3000/minute
Centrifugal Force	750 kN
Weight	3330-3620 kg

DIMENSIONS: KOBELCO SK350 LC EXCAVATOR			
Α	Overall length	11300	
В	Overall height (to top of boom)	3420	
С	Overall width	3190	
D	Overall height (to top of cab)	3200	
E	Ground clearance of rear end*	1190	
F	Ground clearance*	485	
G	Tail swing radius	3600	
G'	Distance from centre of swing to rear end	3600	
Н	Tumbler distance	4050	
I	Overall length of crawler	4960	
J	Track gauge	2590	
K	Shoe width	600	
L	Overall width of upperstructure	2980	

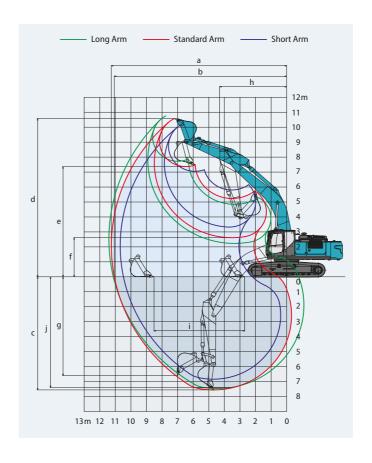




With SG-75 Vibratory Hammer Attachment



WORKING RANGE: BOOM REACH AND RADIUS/OVER HANG

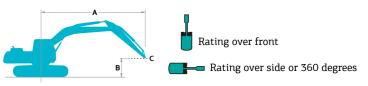


W	ORKING RANGES		
A	Maximum digging reach	mm	11260
В	Maximum digging reach (ground level)	mm	11060
С	Maximum digging depth	mm	7560
D	Maximum digging height	mm	10580
E	Maximum dumping clearance	mm	7370
F	Minimum dumping clearance	mm	2620
G	Maximum vertical wall digging depth	mm	6110
н	Minimum swing radius	mm	4310
I	Horizontal digging stroke at ground level	mm	5820
J	Digging depth for 2.4 m (8') flat bottom	mm	7400
Bu	Bucket capacity ISO heaped m ³		1400

LIFTING CAPACITIES:

- A Reach from swing centerline to arm top
- B Arm top height above/below ground
- C Lift point

Relief valve setting: 37.8 MPa {385 kgf/cm²}



	SK350 LC Boom: 6.50m Arm: 3.30m Bucket: without Shoe: 600mm (Heavy Lift)															
	A	1.5	5m	3.0)m	4.!	5m	6.0)m	7.5	5m	9.0)m	At Max	. Reach	
В		—	—	1	—	1	—	—	 	1	—	—	—	1	+	Radius
9.0m	kg													*6,370	*6,370	6.56 m
7.5m	kg									*7,810	*7,810			*5,840	*5,840	7.86 m
6.0m	kg									*7,930	*7,930			*5,640	*5,640	8.71 m
4.5m	kg							*9,720	*9,720	*8,490	7,700	*7,850	5,750	*5,650	5,480	9.25 m
3.0m	kg					*15,090	*15,090	*11,160	10,160	*9,230	7,360	*8,160	5,600	*5,830	5,110	9.25 m
1.5m	kg					*17,300	14,250	*12,430	9,580	*9,940	7,040	8,400	5,430	*6,200	4,980	9.54 m
G.L.	kg					*18,060	13,770	*13,170	9,200	*10,400	6,810	8,270	5,320	*6,830	5,070	9.33 m
-1.5m	kg			*15,390	*15,390	*17,700	13,670	*13,230	9,040	*10,420	6,700			*7,890	5,410	8.85 m
-3.0m	kg	*17,520	*17,520	*22,280	*22,280	*16,380	13,810	*12,490	9,080	*9,690	6,750			*8,640	6,160	8.07 m
-4.5m	kg			*18,200	*18,200	*13,800	*13,800	*10,490	9,330					*8,540	7,810	6.88 m



KOBELCO SK380 SRLC EXCAVATOR RIG

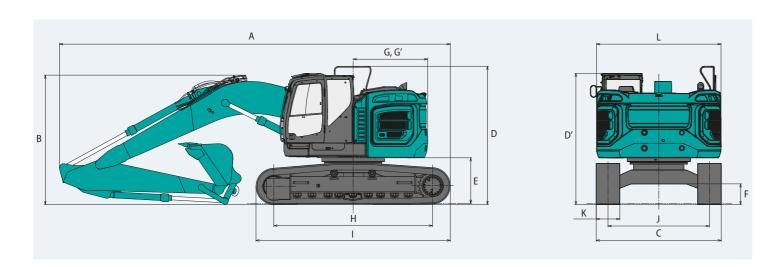
Base Machine	SK380 SRLC
Engine Type	HINO JOSEYD-KSDS
Engine Power	200 kW
Fuel Tank	350 litres
Hydraulic Tank	440 litres
Undercarriage	Fixed
Operating Weight	36.5 tonnes

Vibro Hammer	Movax SG60
Static Moment	6.1 kgm
Frequency	2600/minute
Centrifugal Force	600 kN
Weight without Clamp	2600 kg

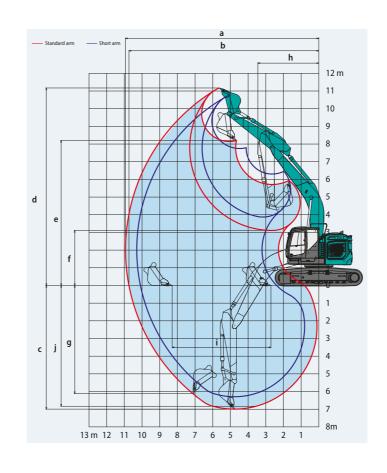
DIM	TENSIONS: KOBELCO SK380 SRLC EXC	AVATOR
Α	Overall length	9470
В	Overall height (to top of boom)	3100
С	Overall width	3190
D	Overall height (to top of handrail)	3530
D'	Overall height (to top of cab)	3360
E	Ground clearance of rear end*	1160
F	Ground clearance*	485
G	Tail swing radius	1900
G'	Distance from centre of swing to rear end	1900
Н	Tumbler distance	4050
I	Overall length of crawler	4960
J	Track gauge	2590
K	Shoe width	600
L	Overall width of upperstructure	3180



With SG-60 Vibratory Hammer Attachment



WORKING RANGE: BOOM REACH AND RADIUS/OVER HANG

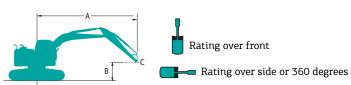


w	ORKING RANGES		
Α	Maximum digging reach	mm	10930
В	Maximum digging reach (ground level)	mm	10740
С	Maximum digging depth	mm	6990
D	Maximum digging height	mm	11170
E	Maximum dumping clearance	mm	8150
F	Minimum dumping clearance	mm	3110
G	Maximum vertical wall digging depth	mm	6110
н	Minimum swing radius	mm	3450
I	Horizontal digging stroke at ground level	mm	5590
J	Digging depth for 2.4 m (8') flat bottom	mm	6830

LIFTING CAPACITIES:

- A Reach from swing centerline to arm top
- B Arm top height above/below ground
- C Lift point

Relief valve setting: 37.8 MPa {385 kgf/cm²}



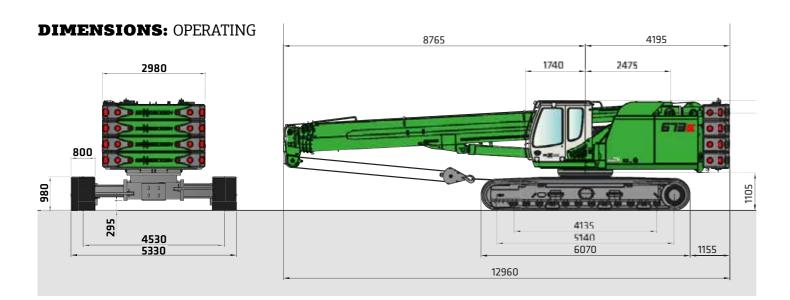
		SK380SRLC Boom: 6.20m Arm: 2.40m Counterweight: 9,000kg Shoe: 600mm (Heavy Lift)										
	A	3.0)m	4.!	5m	6.0)m	7.	5m	At Max	. Reach	
В		1		<u> </u>	—	1	—	1	—	1	—	Radius
9.0m	kg									*8,950	*8,950	5.04 m
7.5m	kg					*8,630	*8,630			*7,680	7,080	6.72 m
6.0m	kg			*10,240	*10,240	*9,010	8,450	*8,510	5,870	*7,230	5,540	7.74 m
4.5m	kg			*13,030	12,370	*10,150	8,040	*8,840	5,720	*7,150	4,780	8.36 m
3.0m	kg					*11,540	7,550	9,330	5,500	*7,340	4,410	8.67 m
1.5m	kg					*12,610	7,150	9,090	5,280	7,310	4,290	8.71 m
G.L.	kg			*15,460	10,410	12,440	6,940	8,940	5,150	7,530	4,390	8.47 m
-1.5m	kg	*11,100	*11,100	*16,530	10,460	12,390	6,890	8,920	5,130	8,260	4,790	7.94 m
-3.0m	kg	*18,730	*18,730	*14,550	10,650	*11,150	7,010			*8,880	5,720	7.03 m
-4.5m	kg			*10,840	*10,840					*8,260	8,180	5.58 m

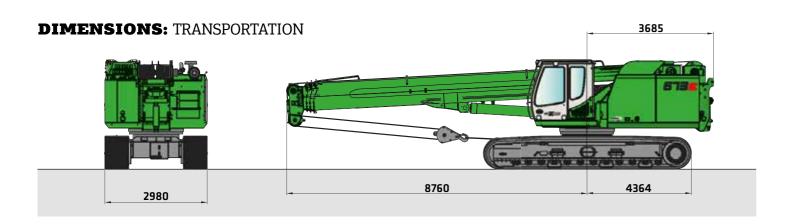


SENNEBOGEN 673R CRAWLER CRANE

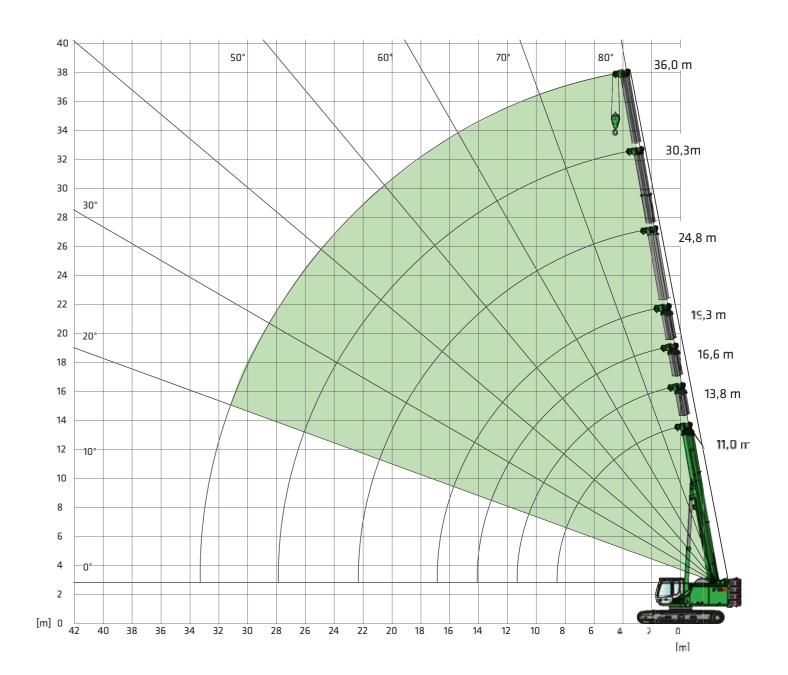
Machine Model	673R
Engine Type	Deutz TCD 6.1 L6
Engine Power	160 kW
Emission Standards	Euro Stage 3a
Fuel Tank Capacity	540 litres
Hydraulic Tank Capacity	765 litres
Undercarriage	Telescopic
Operating Weight	70 tonnes







673R: 360° TELESCOPIC BOOM 36M



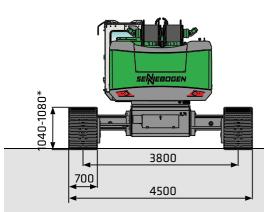


SENNEBOGEN 653E CRAWLER CRANE

Machine Model	653E
Engine Type	Cummins QSB 4.5
Engine Power	119 kW
Emission Standards	Euro Stage IV
Fuel Tank Capacity	360 litres
Hydraulic Tank Capacity	500 litres
Undercarriage	Telescopic
Operating Weight	50.2 tonnes

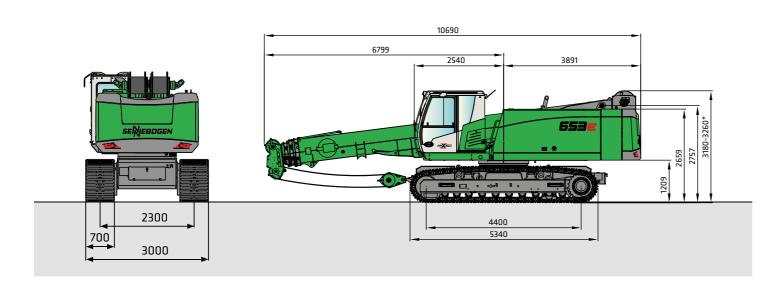


DIMENSIONS: OPERATING

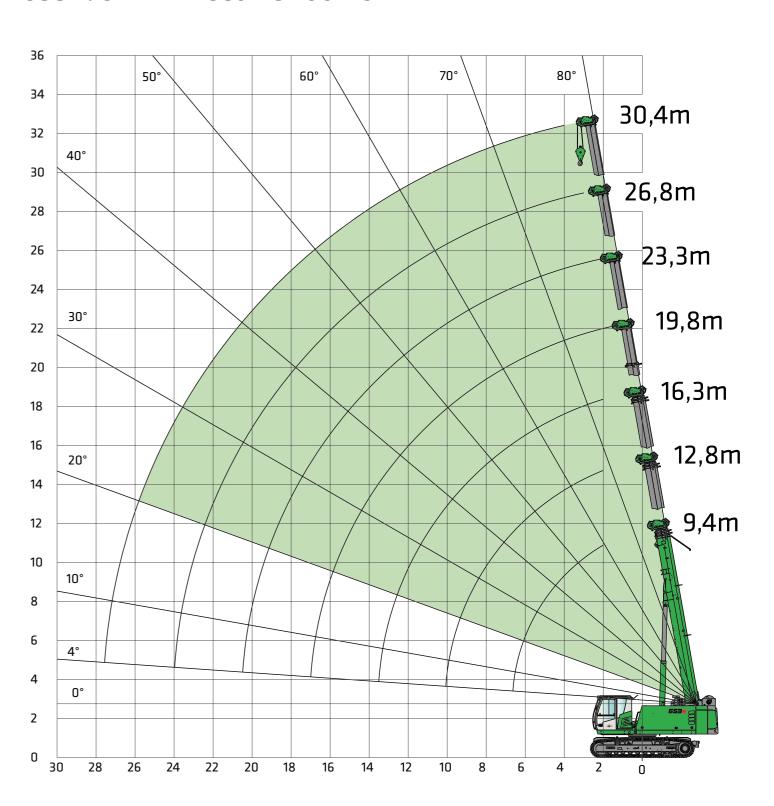




DIMENSIONS: TRANSPORTATION



653E: 360° TELESCOPIC BOOM 30M



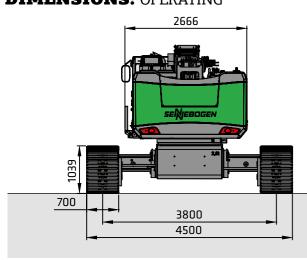


SENNEBOGEN 643R CRAWLER CRANE

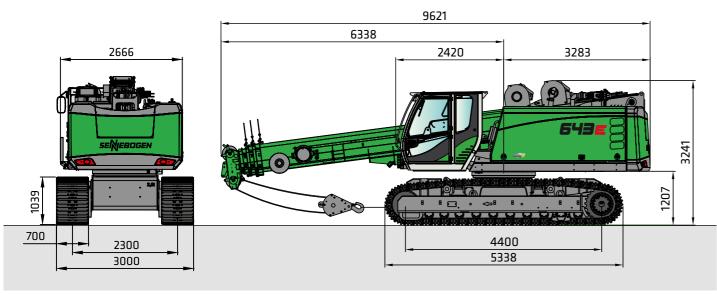
Machine Model	643R
Engine Type	Cummins QSB 4.5
Engine Power	119 kW
Emission Standards	Euro Stage 3a
Fuel Tank Capacity	360 litres
Hydraulic Tank Capacity	500 litres
Undercarriage	Telescopic
Operating Weight	42 tonnes



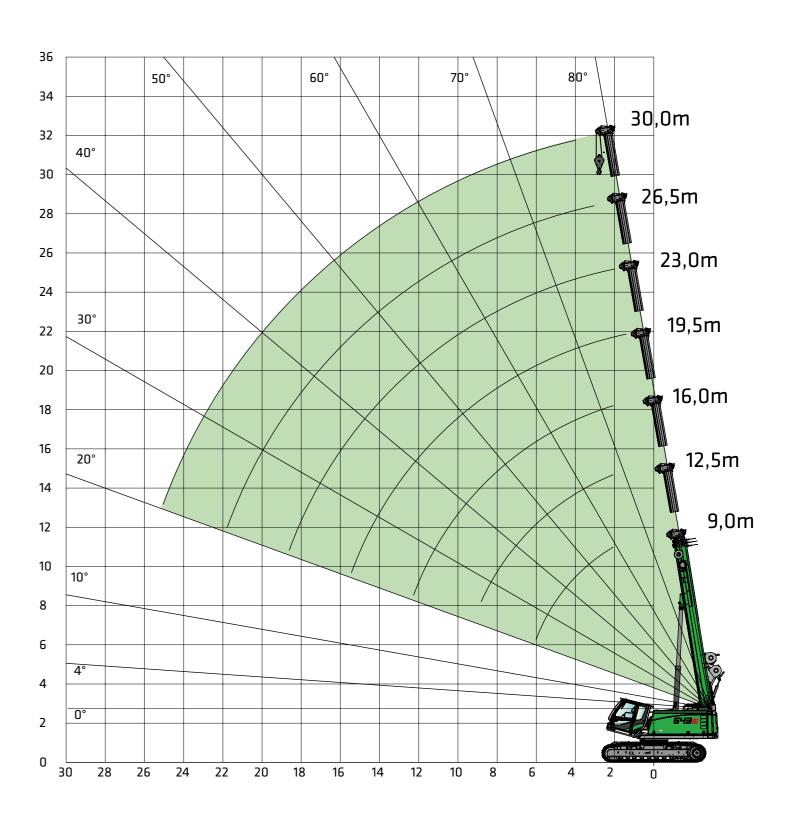
DIMENSIONS: OPERATING



DIMENSIONS: TRANSPORTATION



643R: 360° TELESCOPIC BOOM 30M

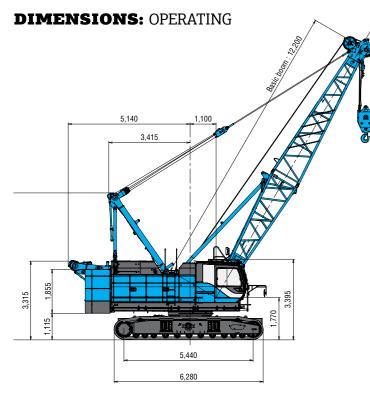


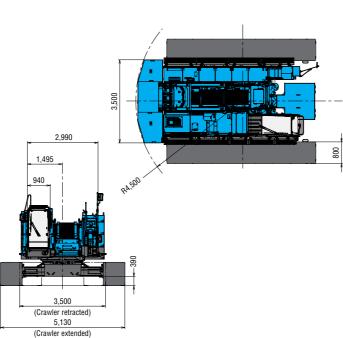


KOBELCO CKG900E CRAWLER CRANE

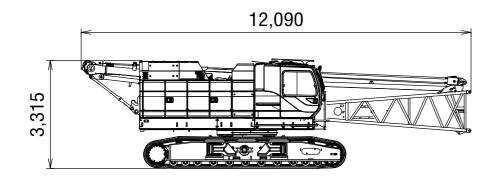
Machine Model	CKG900E
Engine Type	HINO JOSE-YD
Engine Power	213 kW
Emission Standards	Euro Stage 5
Fuel Tank Capacity	400 litres
Hydraulic Tank Capacity	440 litres
Undercarriage	Telescopic
Operating Weight	90 tonnes

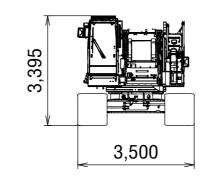




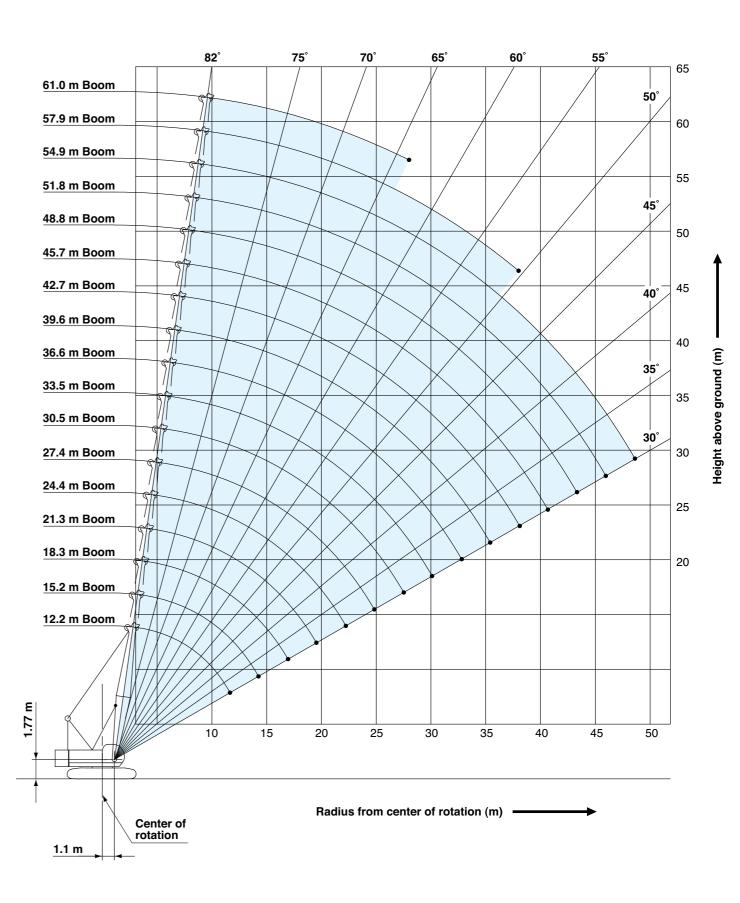


DIMENSIONS: TRANSPORTATION





CKG900E: CRANE BOOM





SENNEBOGEN 673R CRAWLER CRANE

LIFT CAPACITIES: MAIN BOOM

	Boom Length (m)								
	11,0	13,8	16,6	19,3	24,8	30,3	36,0		
Counterweight	.	.	.		■.■	.	. .		
(t)	17,4	17,4	17,4	17,4	17,4	17,4	17,4		
Carbody	<u></u> ====	<u></u> ====	 <u>+</u> =	<u></u>	⋛ 	<u></u>	<u></u>		
Counterweight (t)	0,0	0,0	0,0	0,0	0,0	0,0	0,0		
Undercarriage Track Width		₽ = 1		. <u>≓</u>	 		ı ≓ ı		
(m)	4,6	4,6	4,6	4,6	4,6	4,6	4,6		
Working Radius	(m)								
2,0	70,0						ĺ		
2,5	70,0						Ì		
3,0	67,2								
4,0	56,0	39,5	37,8	29,0	22,5	21,0			
5,0	44,9	39,5	32,9	28,5	22,5	20,1	14,5		
6,0	37,3	36,9	29,1	25,1	22,1	18,4	14,5		
7,0	31,7	31,4	26,1	22,5	19,9	16,9	14,2		
8,0	26,5	25,8	23,6	20,3	18,0	15,4	13,4		
9,0		21,4	21,5	18,5	16,4	14,1	12,6		
10,0		18,1	18,6	16,9	15,0	13,0	11,8		
12,0		15,5/11,0m	16,0	12,8	12,8	11,0	10,2		
14,0			12,2/13,0m	9,8	10,1	9,5	8,7		
16,0				7,7	7,9	8,3	7,5		
18,0					6,3	6,8	6,5		
20,0					5,1	5,5	5,7		
22,0					4,5/21,0m	4,5	4,8		
24,0						3,7	3,9		
26,0						3,0	3,3		
28,0							2,7		
30,0							2,2		
32,0							1,8		
34,0									
36,0									
38,0									
40,0									
Parts Reeving	14	14	11	9	7	5	3		
i	0%	33%	66%	100%	100%	100%	100%		
ii	0%	0%	0%	0%	33%	66%	100%		
iii	0%	0%	0%	0%	33%	66%	100%		
Reduction of Load (kg)	770	the jib is mounted	at the basic main	boom the rated loa 430	ads have to be reduce 340	ed. 280	240		

SENNEBOGEN 653E CRAWLER CRANE

LIFT CAPACITIES: MAIN BOOM

	Boom Length (m)											
i	9,4	12,8	16,3	19,8	23,3	26,8	30,4					
Counterweight			.	3.5		4.	-					
(t)	8,9	8,9	8,9	8,9	8,9	8,9	8,9					
Carbody Counterweight	<u></u>	₽ 	₽ 	₽ ≐ ₽	₽ ≐ ₽	┋╧┇	┋╼┋					
(t)	5,5	5,5	5,5	5,5	5,5	5,5	5,5					
Undercarriage		 	i≡i		 							
Track Width (m)	3,8	3,8	3,8	3,8	3,8	3,8	3,8					
Working Radius												
2,0	50,0	31,0	28,0	15,6	14,5	İ						
3,0	45,0	31,0	25,0	15,6	14,5	12,7						
4,0	38,0	31,0	22,0	15,6	14,5	12,6	9,2					
5,0	30,0	28,0	19,3	15,6	14,2	12,4	9,2					
6,0	22,0	22,5	16,9	14,9	13,6	11,9	9,2					
7,0		17,5	15,0	13,6	12,5	11,1	9,1					
8,0		14,2	13,5	12,2	11,2	10,3	8,7					
9,0		11,7	11,7	11,1	10,2	9,4	8,2					
10,0			9,9	10,1	9,3	8,6	7,8					
11,0			8,5	8,9	8,5	8,0	7,3					
12,0			7,4	7,7	7,9	7,3	6,8					
13,0			6,4	6,8	7,1	6,8	6,4					
14,0				6,0	6,2	6,3	5,9					
15,0				5,4	5,6	5,8	5,6					
16,0				4,8	5,0	5,2	5,2					
17,0					4,5	4,7	4,9					
18,0					4,1	4,3	4,4					
19,0					3,7	3,9	4,1					
20,0					3,3	3,6	3,7					
21,0						3,3	3,4					
22,0						3,0	3,1					
23,0						2,7	2,9					
24,0							2,6					
25,0							2,4					
26,0							2,2					
Parts Reeving	4	3	3	2	2	2	1					
i	0%	50%	100%	100%	100%	100%	100%					
ii	0%	0%	0%	25%	50%	75%	100%					
iii	0%	0%	0%	25%	50%	75%	100%					
Reduction of Load	580	420	330	270	230	200	180					



SENNEBOGEN 643R CRAWLER CRANE

LIFT CAPACITIES: MAIN BOOM

			Во	om Length	(m)		
	9,0	12,5	16,0	19,5	23,0	26,5	30,0
Counterweight					.	.	
(t)	7,0	7,0	7,0	7,0	7,0	7,0	7,0
Carbody Counterweight (t)	4,0	≟ =∎ 4,0	≟	≟ 4,0	≟ =∎ 4,0	≟ =∎ 4,0	≟= 4,0
Undercarriage Track Width (m)	∓ 3,8	≟ 3,8	₽ 3,8			≟ 3 ,8	
Working Radius		3,0	3,0	3,0	3,0	3,0	3,0
2,0	40,0		Ì		1	ı	
3,0	35,0	20,0	15,0	14,0	11,0	8,9	5,0
4,0	30,2	20,0	15,0	14,0	11,0	8,9	5,0
5,0	25,5	20,0	15,0	13,3	11,0	8,6	5,0
6,0	18,6	18,5	14,9	12,0	10,3	8,3	5,0
7,0	12,2/6,2m	14,3	13,2	10,9	9,5	7,8	5,0
8,0	12,27 0,2.11	11,5	11,4	9,8	8,7	7,4	5,0
9,0		9,5	9,4	9,0	7,9	6,9	5,0
10,0		7,5/9,6m	8,0	8,3	7,1	6,4	5,0
11,0		,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	6,8	7,2	6,5	5,9	5,0
12,0			5,9	6,2	5,9	5,5	5,0
13,0			5,0	5,4	5,5	5,1	4,7
14,0			-,	4,8	5,0	4,8	4,4
15,0				4,2	4,5	4,5	4,1
16,0				3,7	4,0	4,2	3,8
17,0				3,5/16,6m	3,6	3,7	3,6
18,0					3,2	3,4	3,3
19,0					2,9	3,0	3,1
20,0					2,6	2,7	2,9
21,0					2,5/20,1m	2,5	2,6
22,0						2,2	2,4
23,0						1,9/23,6m	2,2
24,0							2,0
25,0							1,8
26,0							1,6
27,0							1,5
28,0							1,5/27,1m
Parts Reeving	10	6	5	4	4	3	2
i	0%	50%	100%	100%	100%	100%	100%
ii	0%	0%	0%	25%	50%	75%	100%
iii	0%	0%	0%	25%	50%	75%	100%

KOBELO CKG900E CRAWLER CRANE

LIFT CAPACITIES: MAIN BOOM

					В	oom Le	ngth (r	n)				
	12.2	15.2	18.3	21.3	24.4	27.4	30.5	33.5	36.6	39.6	42.7	45.7
Countan		.	4.	.	4.	4.		■. ■	#. #	4.	■.■	#
Counter- weight (t)	↓ ↓ 31.9	↓ ↓ 31.9	→ → 31.9	1 1 31.9	1 + 31.9	↓ ↓ 31.9	+ + 31.9	↓ ↓ 31.9	↓ ↓ 31.9	→ → 31.9	↓ ↓ 31.9	1 + 31.9
3.33 (2)		-										
Carbody	<u>-</u>	₽±₽	₽±₽	₽╧₽	₽≐₽	₽±₽	<u>-</u> -	: =:	₽ <u></u>	₽¥₽	<u></u>	₽ ≐ ₽
Weight (t)	14.4	14.4	14.4	14.4	14.4	14.4	14.4	14.4	14.4	14.4	14.4	14.4
Undercar-		₽ = ₽	₽ = ₽		 =.		. . =.			
riage Track Width (m)	5.1	5.1	5.1	5.1	5.1	5.1	5.1	5.1	5.1	5.1	5.1	5.1
Working Rad					J.,_	J.1_	0.1_	J.,_		J.,_		3,1
3.6	100.0*				1							
3.9	90.0	89.9	89.7									
4.0	89.0	88.9	88.7	4.3m/68.4								
4.5	79.6	79.5	79.4	68.4	4.7m/68.4							
5.0	72.1	71.9	71.8	68.4	67.6	5.1m/57.0						
5.5	65.8	65.7	65.5	63.6	60.6	57.0	5.6m/54.0					
6.0	60.5	60.3	59.9	57.5	54.9	52.7	50.5	45.6	6.4m/41.9	6.8m/34.2		
7.0	48.6	48.5	48.4	48.1	46.2	44.5	42.9	41.5	40.0	34.2	7.3m/31.9	7.7m/28.0
8.0	39.9	39.8	39.7	39.9	39.8	38.5	37.2	36.1	35.0	33.9	31.4	27.8
9.0	33.8	33.7	33.6	33.8	33.6	33.6	32.8	31.9	31.0	30.1	29.2	26.2
10.0	29.3	29.2	29.1	29.2	29.1	29.0	28.9	28.5	27.7	27.0	26.2	24.5
12.0	11.8m/22.9	22.9	22.8	22.9	22.8	22.7	22.6	22.6	22.5	22.3	21.7	21.2
14.0		18.8	18.6	18.8	18.6	18.5	18.4	18.4	18.3	18.3	18.1	18.0
16.0		14.4m/18.1	15.7	15.8	15.7	15.6	15.5	15.4	15.3	15.3	15.2	15.1
18.0			17.0m/14.5	13.7	13.5	13.4	13.3	13.2	13.1	13.1	12.9	12.9
20.0				19.6m/12.2	11.8	11.7	11.6	11.5	11.4	11.4	11.2	11.2
22.0					10.5	10.4	10.2	10.2	10.0	10.0	9.9	9.8
24.0					22.3m/10.3	9.3	9.1	9.1	8.9	8.9	8.7	8.7
26.0						24.9m/8.8	8.2	8.2	8.0	8.0	7.8	7.7
28.0							27.6m/7.6	7.4	7.2	7.2	7.0	7.0
30.0								6.8	6.6	6.5	6.4	6.3
32.0								30.2m/6.7	6.0	6.0	5.8	5.7
34.0									32.9m/5.8	5.5	5.3	5.2
36.0										35.5m/5.1	4.8	4.8
38.0											4.4	4.4
40.0											38.1m/4.4	4.0
44.0												40.8m/3.9
Reeves	8	8	8	6	6	5	5	4	4	3	3	3

Ratings according to EN13000. Ratings shown in (blue boxes) are determined by the strength of the boom or other structural components.

Lifting capacities may vary depending on hook used or with/without auxiliary sheave. Please refer rated chart in operator's cabin. * The value are theoretical result.



PLANT LOADINGS

PILING RIG & CRAWLER CRANE BEARING PRESSURES

Plant						Case 1 I Standing or	•		Loading Iling	Case 2 l Instal	Loading lation	Case 2 I Extract	Loading tion [1]	Notes [2]
Manufacturer & Model	Track Pad Width (m)	Track Bearing length (m)	Working Weight (Te)	Max Crowd Force (kN)	Max Extraction Force (kN)	Max Rectangular Bearing Pressure (kN/m²)	Equivalent Track Bearing Length (m)	PLEASE NOTE: Track Loadings and Track Lengths quoted are based strictly on the following operational limitations noted below for each item of plant.						
Sheet Piling Rigs														
ABI TM 20 LR Long Reach	0.90	4.40	84	180	180	260	2.38	N/A	N/A	199	2.36	315	1.87	Maximum Working Radius = 8.04m Maximum Crowd Force = 120kN Maximum Extraction Force = 120kN
ABI TM 20	0.90	4.50	74	200	235	194	2.64	N/A	N/A	218	1.48	371	1.51	Maximum Working Radius = 6.05m Maximum Crowd Force = 145kN Maximum Extraction Force = 185kN
ABI TM 18/22 HD	0.70	4.80	82	120	200	203	3.49	N/A	N/A	215	2.52	313	2.64	Maximum Working Radius = 5.70m Maximum Crowd Force = 120kN Maximum Extraction Force = 200kN
ABI TM 13/16 SL	0.60	3.85	50	90	175	200	3.08	N/A	N/A	204	2.32	291	2.30	Maximum Working Radius = 5.79m Maximum Crowd Force = 58kN Maximum Extraction Force = 109kN
ABI TM 12/15 LR Long Reach	0.70	4.51	62	90	100	194	2.77	N/A	N/A	121	3.56	320	1.70	Maximum Working Radius = 8.08m Maximum Crowd Force = 72kN Maximum Extraction Force = 80kN Handling of Sheet Pile is NOT Permitted
Bauer RTG 21T	0.70	4.42	78	140	260	343	2.23	N/A	N/A	222	2.91	372	1.85	Maximum Working Radius = 5.91m Maximum Crowd Force = 60kN Maximum Extraction Force = 20kN
Kobelco SK380 SRLC Excavator Piling Rig	0.80	4.05	40	60	60	154	2.29	201	1.91	162	1.76	178	2.08	Maximum Working Radius = 8.0m Maximum Load = 5Te (Bundle Piles)
Kobelco SK350 LC Excavator Piling Rig	0.80	4.05	40	60	60	128	2.90	148	2.41	165	1.80	171	2.20	Maximum Working Radius = 8.0m Maximum Load = 5Te (Bundle Piles)
Crawler Cranes														
Sennebogen 673R	0.70	5.10	70	N/A	N/A	184	2.66	291	2.46	-	-	-	-	Maximum Radius / Maximum Load Minimum Radius / Maximum Load
Sennebogen 653E	0.70	4.40	50	N/A	N/A	94	3.82	241	1.92	-	-	-	-	Maximum Radius / Maximum Load Minimum Radius / Maximum Load
Sennebogen 643R	0.70	4.40	42	N/A	N/A	121	2.94	237	3.28	-	-	-	-	Maximum Radius / Maximum Load Minimum Radius / Maximum Load
Kobelco CKG900E	0.80	5.44	90	N/A	N/A	163	3.40	357	2.78	-	-	-	-	Maximum Radius / Maximum Load Minimum Radius / Maximum Load 3.5Te Hook Block / 3 Fall Duties Jib Length = 24.4m (Min) / 45.7m (Max)

^{1.} Extraction load case applicable to both pile extraction and pre-augering activities.

^{2.} Maximum crowd and extraction force only possible with reduced reach.



NOISE ASSESSMENTS

GENERAL INTRODUCTION

All piling activity generates noise. The consequences of the additional noise may be a health hazard or a cause of annoyance to the general public.

Construction site noise levels, in decibels (dB), are usually 'A-weighted' to give measurements and levels relative to the sensitivity of the human ear.

The accepted measure of noise is the equivalent 'A-weighted' sound pressure level, L_{Aeq} , relative to a specified time period, T.

A number of factors are likely to affect the acceptability of noise arising from construction sites which include:

- Site location.
- Existing background noise levels.
- Duration of site operations.
- · Hours of work.
- · Provision of additional mitigation measures.

If noise levels increase from the background level by 3dB (A) then the change is just perceptible. If the noise level increases by 10dB (A) then it is perceived as being twice as loud. A 20dB (A) increase implies a tenfold increase in noise level.

DESIGN STANDARDS & REFERENCES

- BS 5228 (2009) Part 1 Code of practice for noise and vibration control on construction and open sites.
- Control of Pollution Act (CoPA) 1974 Applications for prior consent for work on construction sites.

FORMULA FOR CALCULATION OF NOISE

The base sound pressure levels for specialist piling equipment can be obtained from relevant manufaturers and typical values are summarised below:

- High Frequency Vibrohammers ie.
 MRZV 18V L_{nA} = 115 dB(A)
- Hydraulic Drop Hammers $L_{DA} = 125 dB$ (A).

Noise attenuates with distance from the source which can be defined by empirical equations.

Therefore to calculate an equivalent continuous A-weighted sound level over an 'effective' working day duration the following equations are used:

$$L_{Aeq} = L p A - 20 log (R) - 8 For R < 25m$$

 $L_{Aeq} = L p A - 25 log (R) - 1 For R > 25m$

Where, R = Distance from Noise Source (m).

In general, piling operations will typically run between 10% and 50% of the working day.

Consequently the previously presented formula can be further modified according to the following equation:

$$L_{Aeq}$$
 (red) = L_{Aeq} + 10 log ($\frac{t1}{T}$)

Where:

t1 = Actual piling time. T = Total working period per day.

TYPICAL WORKED EXAMPLE

Assuming the sheet piles are installed using an ABI MRZV 18V vibratory hammer the following are noted:

• Base Sound Pressure Level L_{DA} = 115 dB (A)

Therefore the following attenuated noise level of various distances from the source can be calculated as follows:

Distance 'R' (m)	2.0	5.0	10.0	25.0
Attenuated noise level L_{Aeq} dB(A)	101	93	87	79
Distance 'R' (m)	50.0	75.0	100.0	150.0

Assuming a maximum piling duration of 5 hours per day (ie. 50%) the calculated values above can be further modified as follows:

Distance R (III)	2.0	3.0	10.0	25.0
Attenuated noise level L_{Aeq} (red) dB(A)	98	90	84	76
Distance 'R' (m)	50.0	75.0	100.0	150.0

69 64

61 57

Attenuated noise level L_{Aeq} (red) dB(A)

Consequently the attenuated noise levels, as adjusted for time of piling operations, are reduced at various distances from the noise source by approximately 3 dB(A).

GROUND BORNE VIBRATION ASSESSMENTS

GENERAL INTRODUCTION

The installation of steel sheet piles using vibratory installation techniques will inevitably result in ground borne vibrations. The vibration level is a function of the power rating and frequency of the vibrohammer from which peak particle velocities and particle accelerations can be calculated based on to some extent the type and nature of soils. The vibration levels at the source will naturally attenuate with distance.

DESIGN STANDARDS & REFERENCES

- **BS 5228 (1992) Part 4** Code of practice for noise and vibration control applicable to piling.
- **BS 5228 (2009) Part 2** Code of practice for noise and vibration control applicable to piling.
- British Steel (CORUS) Control of vibration and noise during piling.
- **BS 7385 Part 1** Guide for measurement of vibrations and evaluation of their effects on buildings.
- **BS 7385 Part 2** Guide on damage levels from ground borne vibrations.

FORMULA FOR CALCULATION OF PEAK PARTICLE VELOCITY (PPV)

For vibratory driven sheet piles, the maximum peak particle velocity (PPV) can be derived from the following empirical formula:

$$V res = \frac{C^* \sqrt{W}}{r}$$

Where

- V res = Maximum peak particle velocity (mm/sec).
- C = Soil Hammer Factor (Recommended as 1.0 for vibratory hammer).
- W = The maximum hammer energy per cycle (J).
- r = Horizontal distance from piling operations (m).

TYPICAL WORKED EXAMPLE

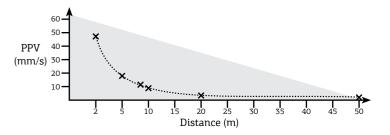
Assuming the sheet piles are installed using an ABI MRZV 18S Vibratory Hammer the following are noted:

- Stated Power Rating = 433 kW.
- Frequency = 2250 rpm (37Hz).
- Energy = 433 kW/37 Hz.
 - = 11702J/Cycle.
- Efficiency = 80%
- Hammer energy (w) = $11702J \times 80\% = 9362J$

Therefore an assessment of the possible vibration levels can be undertaken using the formula presented in BS5228 Part 4 (1992).

The results of this example are presented below:

Distance (m)	2.0	5.0	8.0	10.0
Predicted PPV (mm/s)	48.4	19.4	12.1	9.7
Distance (m)	12.0	15.0	20.0	50.0



FURTHER COMMENTS

The revised standard, BS5228 Part 2 (2009) presents an equation for vibratory installation of piles which is based on percentage confidence levels based on the predicted vibration not being exceeded.

This method is entirely empirical and does not take account of soil conditions or hammer type.

Experience suggests there is some correlation with the BS5228 Paart 2 (1992) method based on 33.3% probability of exceeding confidence levels.





GUIDANCE ON PILING PLATFORM REQUIREMENTS

GENERAL INTRODUCTION

This document is intended for use by designers and engineers considering the piling platform requirements for a project utilising Sheet Piling (UK) Ltd equipment and it only applies to ground supported working platforms for tracked plant construction on granular material.

The information is based upon details supplied by the plant manufacturers and Sheet Piling (UK) Ltd own experiences of the plant performance.

To produce the bearing pressures an analysis has been conducted in accordance with the agreed procedures of the FPS and cover the typical working envelope within which piling plant is operated. Further analysis should be undertaken when operating equipment outside of this envelope and when the situation requires different loads or constraints from those noted within this document.

A piling platform designer should take into account any imposed loading by other plant, the ground conditions, the effects of weather, platform deterioration with time, soft spots and the platform maintenance regime.

In accordance with the BRE guidance document (published June 2004) on Design, Installation and Maintenance of Working Platforms the loads for each rig have been analysed and are presented for the two load cases of Case 1 and Case 2.

Case 1 loading applies to the situation when the rig or crane operator is unlikely to be able to aid recovery from an imminent platform failure.

Operations in which this type of loading condition applies could include standing, travelling and handling.

Case 2 loading applies to the situation when the rig or crane operator can control the load safely, for example by releasing the line load, or by reducing power, to aid recovery from an imminent platform failure.

Operations in which this type of loading condition applies could include installing/extracting a sheet pile, and/or drilling/extracting an auger. Consequently, a lower factor of safety can be adopted for this loading case.

These operations include sheet pile installation, extraction and preaugering (where applicable).

INSTALLATION

The Sheet Piling (UK) Ltd Platform Certificate is mandatory for all sites where a piling rig or attendant plant operates. It must be signed by an authorised representative of the Principal Contractor. This merely confirms that the legal duties required under CDM have been carried out.

The working platform provides access for all piling plant, ancillary plant, deliveries, subcontractors and personnel associated with the piling operations. Properly designed and installed, the working platform could also provide suitable and safe access for following trades for the whole project.

One of the main causes of rig instability is a result of poor definition of the edge of the working platform. In general the working platform should be clearing defined relative to the proposed pile line to suit the method of installation and/or extraction. This ensures sufficient safe working area for the piling personnel and attendance plant.

Where access ramps are used to move between working levels these must be of sufficient gradient and width to allow the piling plant to move safely within the stability constraints of the machine. Ramps must be in a straight line between working areas. Piling rigs and cranes cannot change direction on ramps. Where a change in direction is required, this must be on a flat level platform.

MAINTENANCE, REPAIR AND REINSTATEMENT

The working platform must be kept free draining. Water and arisings which are allowed to build up on the working platform can hide recently constructed piles, trip hazards, unstable ground and excavations.

Obstructions encountered during the piling process will generally required excavation to remove them. This can create a 'soft spot' which can result in the rig overturning. It is essential that any excavations made in the working platform are reinstated to the designed standard, including any reinforcement and separation filter/membrane.

Inspection of the platform should be an ongoing process throughout the design life of the platform. Any damaged areas must be reinstated to the designed standard.

WORKING PLATFORM CERTIFICATE

Project Name		
Work area covered by this certificate		
PART 1: WORKING	PL.	ATFORM DESIGN
Equipment to be used on site		
Maximum Plant Loading		
		ed Plant: Good practice guide to the design, installation, maintenance and ailable for HS BRE Press - Tel: 01344 328 038).
Designer Name		
Designer Organisation		
Contact Telephone		
Is Testing Specified?	No:	Yes: (give details)

PART 2: VERIFICATION BY PRINCIPAL CONTRACTOR

The working platform detailed above has been designed, installed to the design and, if specified, tested to safely support the equipment detailed in Part 1 above. The limits of the platform have been clearly identified on site as necessary.

This working platform will be REGULARLY INSPECTED, MAINTAINED, MODIFIED, REPAIRED and REINSTATED to the as-designed condition after any excavation or damage, throughout the period when the equipment is on the site. A completed copy of this certificate signed by an authorised person from the Principal Contractor shall be given to each user of the working platform prior to commencement of any works on site.

Name & Position	Date	
Organisation	Signature	

Sheet Piling (UK) Ltd are committed to develop this initiative and supports the principle of reducing accidents by the certification of properly designed prepared and maintained working platforms.

